

Implementation of PSS and STATCOM Controllers for Power System Stability Enhancement

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Abstract:- In emerging electric power systems, enlarged communication often lead to the situations where the structure no longer remains in secure operating region. The flexible Ac transmission system (FACTS) controllers can take part in an important role in the power system security enhancement. However, due to high capital investment, it is necessary to locate these controllers optimally in the power system. This paper presents an application of fuzzy control to determine the control signal of static compensator (STATCOM) for improvement of power system stability. STATCOM is a shunt type FACTS device which is used in power system primarily for the purpose of voltage and reactive power control. A fuzzy logic based supplementary controller for Static Compensator(STATCOM) is developed which is used for damping the rotor angle oscillations and to improve the transient stability of the power system. Generator speed and the electrical power are chosen as input signals for the fuzzy logic controller (FLC). A Standard 3-phase, six bus system is taken as test system to evaluate the FACTS device (STATCOM) performance for proposed controllers PI and fuzzy with Power System Stabilizer in multi machine system.

Keywords:- Fuzzy Logic Control, PI Controller, Power System Stabilizer, STATCOM.

I. INTRODUCTION

Flexible ac Transmission Systems (FACTS) devices have emerged in power system because of the development of power electronics components for high voltage and power. The FACTS devices provide higher controllability in power systems by means of power electronic devices. Several FACTS equipments have been already introduced for various applications worldwide, and new types of FACTS are in the stage of being introduced in practice. FACTS technology provides a better ability to varying operational conditions and improves the usage of existing installations. The flexible AC transmission system is akin to high voltage DC and related thyristor developments, designed to overcome the limitations of the present mechanically controlled AC power transmission systems. By using reliable and high-speed power electronic controllers, the technology offers five opportunities for increased efficiency of utilities.

- Greater control of power so that it flows on the prescribed transmission routes.
- Secure loading of transmission lines to levels nearer their thermal limits.
- Greater ability to transfer between controlled areas.
- Prevention of cascading outages.
- Damping of power system oscillation.

The increased interest in these devices is essentially due to two reasons. Firstly, the recent development in high power electronics has made these devices cost effective and secondly, increased loading of power systems, combined with deregulation of power industry, motivates the use of power flow control as a very cost effective means of dispatching specified power transactions. Several emerging issues in competitive power market, namely, as congestion management, enhancement of security and available transfer capability of the system, transmission pricing, etc. have been restricting the free and fair trade of electricity in the open power market. FACTS devices can play a major role in these issues. Moreover, it is important to ascertain the location for placement of these devices because of their considerable costs. The insertion of such devices in electrical systems seems to be a promising strategy to reduce the power flows in heavily loaded lines resulting in increased system loadability, low system loss, improved stability of the network and reduced cost of production. The FACTS devices can be categories as shunt, series, series series and combine shunt-series controllers [1-3] namely, static VAR compensator (SVC), thyristor controlled series capacitor (TCSC), thyristor controlled phase angle regulator (TCPAR), static compensator (STATCOM), static synchronous series compensator (SSSC), unified power flow controller (UPFC), generalized unified power flow controller (GUPFC) and interline power flow controller (IPFC) etc.

Static Var compensator (SVC) improves the system performances by controlling the magnitude of voltage. Thyristor controlled phase angle regulator (TCPAR) controls the phase angle of voltage, while thyristor controlled series compensator (TCSC) changes the effective impedance of transmission line to the system performance. The unified power flow controller (UPFC) offers to combine all three functions in one device [4,5]. The control of system parameters can be carried out concurrently or sequentially with transfer from one type control (phase shift) to another one (series compensation) in real time. The other devices of FACTS controller family are static compensator (STATCOM), static synchronous series compensator (SSSC), generalized unified power flow controller (GUPFC) and interline power flow controller (IPFC) etc. [6-8].

II. STATIC COMPENSATOR

An easy way to comply with the paper formatting requirements is to use this document as a template and simply type your text into it. The STATCOM [9-11] is a state-of-the-art Flexible AC Transmission System (FACTS) technology that uses advanced power semiconductor switching techniques to provide dynamic voltage support, power system stabilization, and enhanced power quality for transmission and distribution system applications. The basic voltage-source converter scheme is shown in Fig. 1.

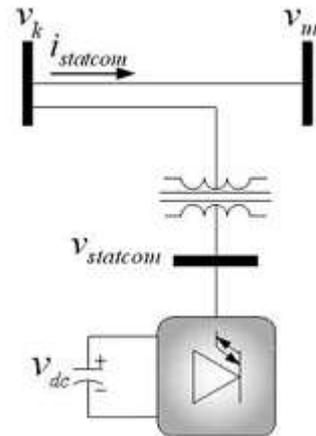


Fig. 1: Static Compensator (STATCOM)

Various techniques for evaluating system damping in the presence of a STATCOM are reported in the literature [12-19]. Most of the above mentioned techniques describe the controller design for damping improvement. In Ref. [12] a multivariable feedback linearization scheme for STATCOM control has been preformed. Also a STATCOM voltage controller has been designed using the loop-shaping technique [13]. Fig. 2 illustrates a block diagram of a STATCOM controller for six bus system.

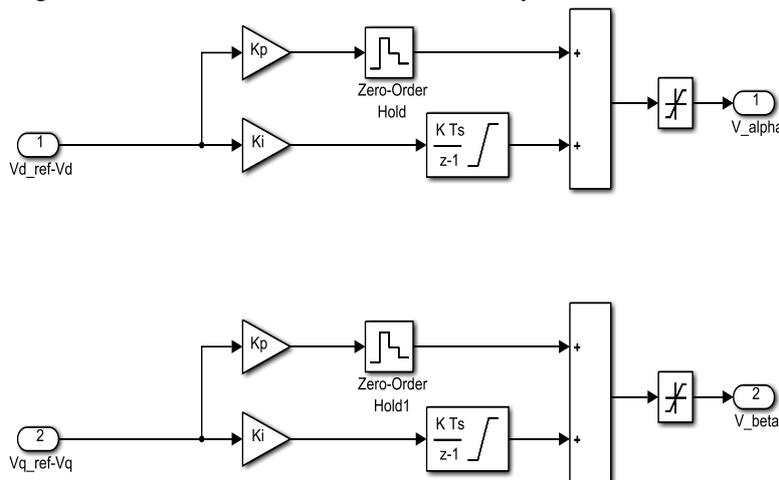


Fig. 2. STATCOM PI controller for six bus system

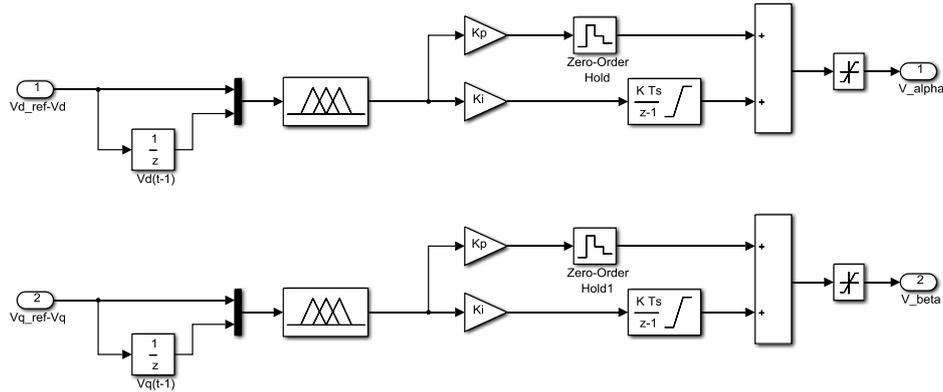
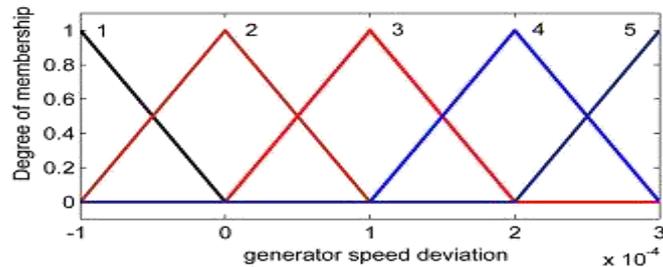


Fig.3. Model of six bus system with STATCOM and PSS control system with FLC.

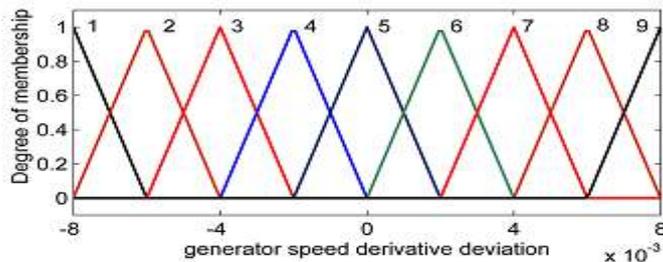
The interactions and multivariable design of STATCOM ac and dc voltage control has been reported in [14]. While most of the control designs are carried out with linearized models, nonlinear control strategies for a STATCOM have also been reported recently [20-22]. The Power System Stabilizer (PSS) is still used as an effective and economical facility to tackle this problem [23]. Reference [24] shows that the appropriate selection of PSS parameters can achieve satisfactory performance during system upsets. Model of six bus system with STATCOM and PSS control system with FLC used in this paper is shown in Fig. 3. Intelligent techniques have been used to design controllers for power systems both with and without a STATCOM. The Fuzzy Logic Controller (FLC) [25] provides a model free approach for PSS and STATCOM controllers and can be effective over the entire range of power system operations. Applications of FLCs have also been reported in [26–28]. However, uncoordinated control of FACTS devices and PSSs may cause destabilizing interactions. To improve overall system performance, many studies were conducted on the coordination between PSSs and FACTS damping controllers [29–34]. This article investigates the stability enhancement problem of power systems considering the combined design of PSS and STATCOM controllers. A FLC has been designed for the PSS. Then, PSO is employed to search for optimal STATCOM controller parameters.

III. FUZZY LOGIC

In 1965, Zadeh proposed fuzzy logic, and it has been effectively utilized in many field of knowledge to solve control and optimization problems [29]. The FLC is a good means to control the parameters when there is not any direct or exact relation between the input and the output of a system, and we only have some linguistic relations in the If-Then form [35]. The use of fuzzy logic has received increased attention in recent years because of its usefulness in reducing the need for complex mathematical models in problem solving [36]. In the power system area, it has been used in stability studies, load frequency control, unit commitment, reactive compensation in distribution networks and other areas.



(a)



(b)

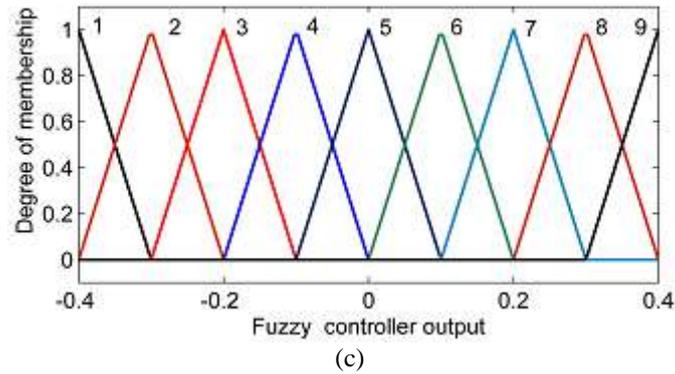
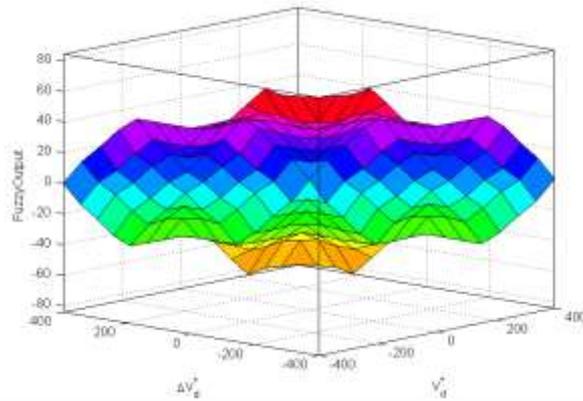


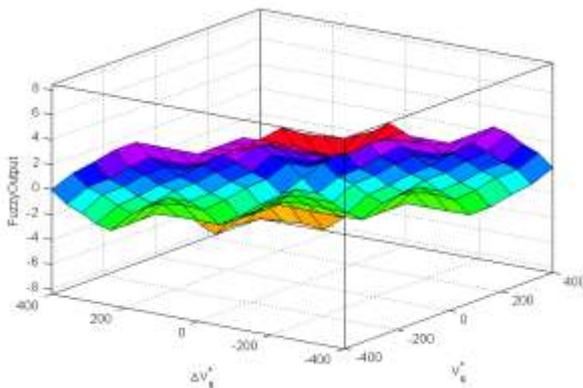
Fig. 4. Membership functions of inputs and output.

A fuzzy control system is made from different blocks such as the numeral quantity converter to fuzzy quantities (fuzzifier interface) block, the fuzzy logical decision maker section, the knowledge base section, and the defuzzier interface block. The following steps are involved in designing a fuzzy PSS controller [37]:

1. Choose the inputs to the FLC. As shown in Fig. 3, only two inputs, the generator speed deviation ($\Delta\omega$) and the generator speed derivative deviation ($\Delta\hat{\omega}$), have been employed in this study. The symbol U_c has been synonymously used to represent the output or decision variable of the FLC.
2. Choose membership functions to represent the inputs in fuzzy set notation. Triangular functions are chosen in this study. Fuzzy representations of the generator speed change, acceleration, and output variable have been illustrated in Fig. 4.
3. A set of decision rules relating the inputs to the output are compiled and stored in the memory in the form of a “decision surface”. The decision surface is provided in Fig. 5.



(a) D-axis fuzzy output



(b) D-axis fuzzy output

Fig. 5. Decision surface of proposed FLC

Table I: Voltage Magnitude of Six Bus System

Bus	PI STATCOM	FUZZY STATCOM
	Voltage in p.u	Voltage in p.u
Bus 1	0	1
Bus 2	0.9	1
Bus 3	0.9	1
Bus 4	0.5	1
Bus 5	0.6	1
Bus 6	0.4	1

IV. SIMULATION RESULTS

In this study, the performance of the combined controllers for the stabilization of a synchronous generator is evaluated by computer simulation studies. A Standard 3-phase, six bus system shown in Fig.6 is taken as test system to evaluate the FACTS device (STATCOM) performance for proposed controllers PI and FUZZY with PSS stabilizer in multi machine system. To evaluate the system a LLLG Fault was established/implemented between the BUS 1 and BUS 4 at a duration of 1.4 to 1.5 sec. Corresponding Voltage waveforms for each with STATCOM controlled by PI and FUZZY is shown below Figs.7-10. From the wave form it's clear that the voltage magnitude of during fault as well as normal condition FUZZY employed STATCOM has superior performance over PI controller, comparison of voltage magnitude also shown table I. Figs.11 and 12 show the angle deviation is lesser than that of PI STATCOM, It's also clearly seen that the performance of PSS also improved.

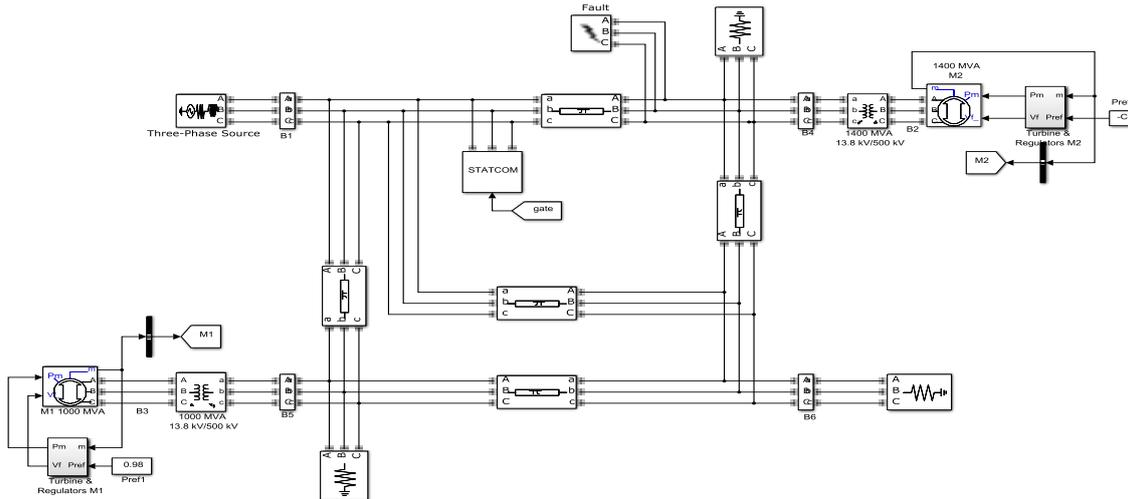


Fig.6. Simulink of a 2-machine, six-bus system with PI-fuzzy controller based STATCOM

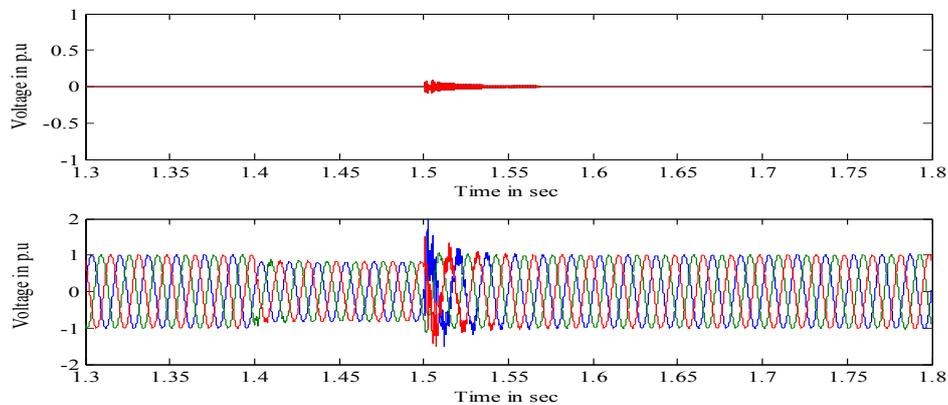


Fig.7. Voltage waveforms of Bus 1 with STATCOM controlled by PI and FUZZY

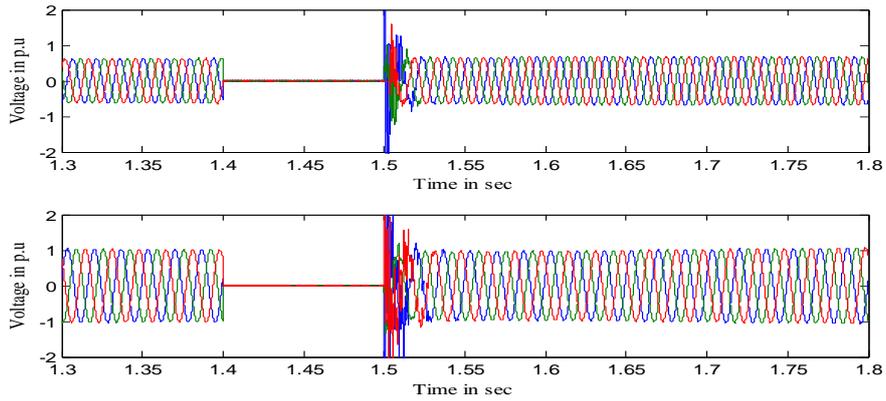


Fig.8. Voltage waveforms of Bus 4 with STATCOM controlled by PI and FUZZY

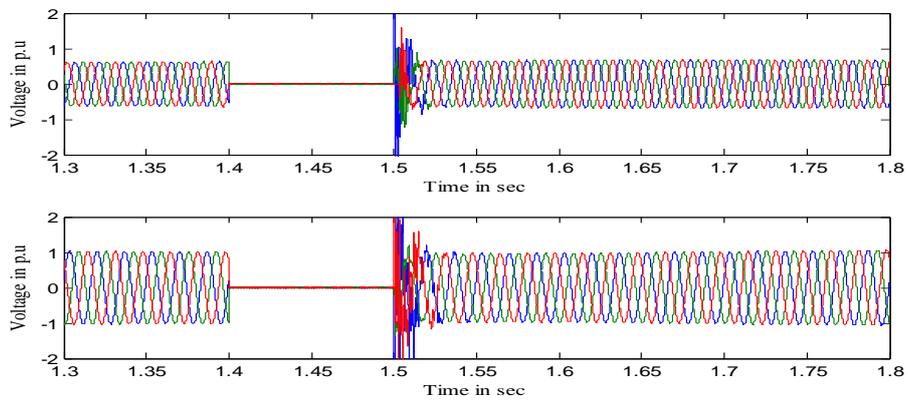


Fig.9. Voltage waveforms of Bus 5 with STATCOM controlled by PI and FUZZY

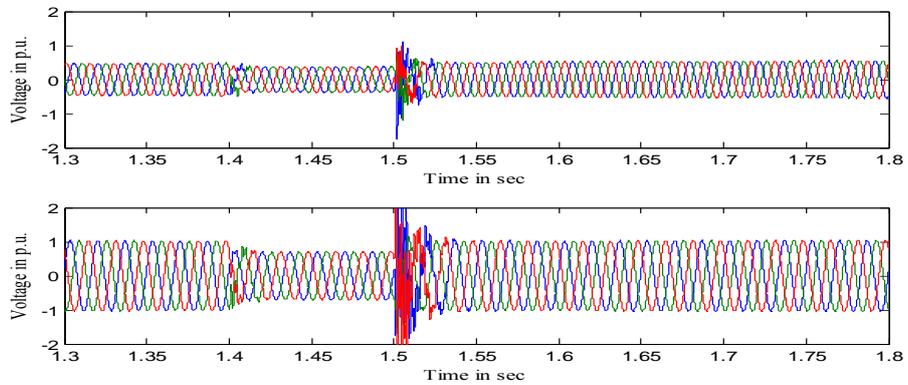


Fig.10 Voltage waveforms of Bus 6 with STATCOM controlled by PI and FUZZY

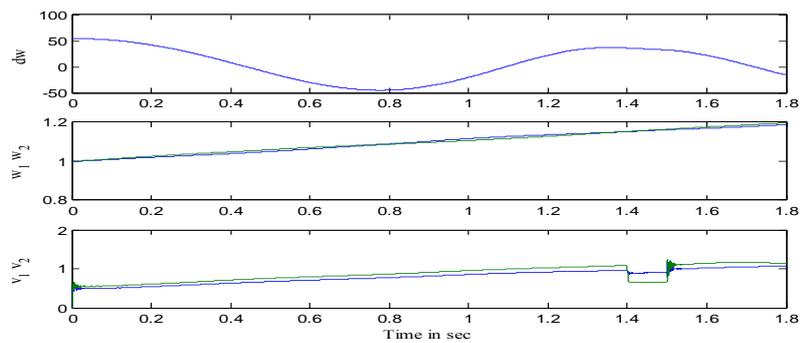


Fig.11 Angle deviation of six bus system M1, M2 with PI control (with PSS)

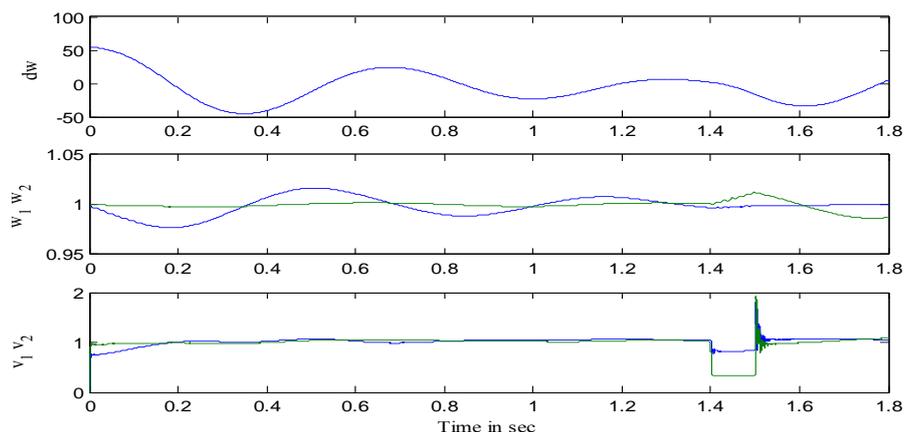


Fig.12 Angle deviation of six bus system M1, M2 with Fuzzy PI control (with PSS)

V. CONCLUSIONS

In this paper a combined design of a STATCOM and a power system stabilizer is used to power system stability enhancement. A fuzzy logic controller and PI controller has designed for the PSS employed to search for the optimal STATCOM controller parameters in a two machine, six bus test system. The optimal design of the controllers has been implemented on a proposed system and discussed. The system performance characteristics demonstrate that the combined design of the STATCOM and PSS controllers is superior to the uncombined design of the controllers.

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